

Universal Vector–Scalar Potential Framework for Inhomogeneous Electromagnetic System and Its Application in Semiclassical Quantum Electromagnetics

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Abstract—In this work, numerical solution to a general electromagnetic (EM) system is studied using a formalism based on the formulas for the E–B–A– ϕ formulas with different gauge conditions. The finite-difference time-domain (FDTD) method is employed to discretize these formulas. In addition, the convolutional perfectly matched layer (CPML) technique is successfully applied to absorb outgoing scattered waves described by the proposed formulas. The gauge invariance of EM fields in inhomogeneous environment is demonstrated by numerical examples. Moreover, the proposed EM framework integrated with the Schrödinger equation is introduced to investigate the mesoscopic phenomenon for light–matter interaction, which is useful to design laser pulses for controlling discrete quantum states. The work offers a simple and general numerical EM

framework, which is essential to bridge the classical EM and quantum mechanical systems.

Index Terms—Convolutional perfectly matched layer (CPML), electromagnetic (EM) system, finite-difference time-domain (FDTD), gauge invariance, vector potential and scalar potential formulas.

I. INTRODUCTION

COMPUTATIONAL electromagnetics (CEM) [1] solves scientific and engineering problems in the EM regime, such as antenna design and optimization [2], ground penetrating radar [3], and electronic devices [4]. When the size of highly integrated devices approaches the nanoscale, several quantum effects, such as spill-out and tunneling effects of electrons [5], and electron transition [6] of atoms and molecules, become increasingly more significant in the EM system and cannot be ignored. In these cases, the classical EM framework is no longer applicable, and these quantum effects will lead to a crucial influence on the performance of photonic and electronic nanodevices. Moreover, these quantum effects can be applied to improve device performance and enhance their functionality. Therefore, the study of the interaction between artificial atoms and external EM fields has become an important and rapidly growing research topic in developing next-generation electronic technologies. Equally important, designing nanodevices and understanding their quantum properties via practical measurements can be extremely expensive and time-consuming. Therefore, the development of an efficient numerical simulation platform for EM response of a nanoscale system is desirable. In fact, some numerical methods based on Maxwell–Schrödinger (M–S) equations [7]–[10] or Maxwell–Bloch equations [11]–[13] have been proposed to model the multiphysics and multiscale problems in a hybrid regime of classical EM and quantum worlds.

In order to bridge the quantum mechanics (QM) and classical EM, an alternative form of Maxwell equations based on the vector potential (\mathbf{A}) and scalar potential (ϕ) formulas is proposed, instead of employing traditional \mathbf{H} fields [14], [15]. However, the second-order partial differential operators acting on the field components in temporal and spatial domains make the numerical implementation of the formulas difficult,

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especially for the perfectly matched layer (PML) technique used to truncate the computational domain and absorb outwardly propagating waves. To investigate the dynamics of charge wave packets in a carbon nanotube, a hybrid method utilizing the transmission line matrix [16] method and finite-difference time-domain (FDTD) approach [17] was employed to solve for the M–S equation. In addition, other hybrid numerical methods, such as the locally one-dimensional (LOD) FDTD method [18] and alternating-direction-implicit (ADI) FDTD method, were also used to solve for the coupled M–S equations for simulating nanodevices [19]. Moreover, based on the solution to the M–S equations, some other multiphysics simulations, such as the modeling of optically controlled quantum states with the Lorenz gauge [20] and the modeling of EM field–particle interaction with the Coulomb gauge [21], [22], were also developed. However, the discussion of the gauge invariance is not comprehensive in the above-mentioned works. In most of these cases, one simply chose a suitable type of field gauge for a specific problem.

In this article, we propose a simple but general **E–B–A– ϕ** formulas that necessitate first-order partial differential operators both in time and space domains. The proposed numerical framework can be used to simulate the EM response of inhomogeneous and dispersive media. In particular, the Lorenz gauge with different forms is applied in the proposed framework to demonstrate the gauge invariance of EM fields. In addition, the convolutional PML (CPML) technique is successfully applied to the coupled EM system described by the proposed formulas. Meanwhile, the accuracy of the numerical framework established and the gauge invariance of EM fields are verified by several numerical examples. Finally, the proposed hybrid EM system coupled to the Schrödinger equation is employed to simulate the transient interaction between an EM control pulse and a single electron that is confined in a quasi-one-dimensional nanoscale potential well. The simulation results show that the proposed method could reproduce a perfect quantum state switching while with a more straightforward numerical solution process. This article is organized as follows. In Section II, the decoupled **A** and ϕ equations and the proposed **E–B–A– ϕ** formulas are presented, and the iteration procedures and the spatial distribution of the field components are introduced. Then, the method of applying the CPML technique to the proposed EM system is introduced. In Section III, several numerical examples are adopted to verify both the accuracy of the proposed method and the gauge invariance of the EM fields. In Section IV, the combination of the proposed EM system with the Schrödinger equation is presented to design the laser pulse for controlling discrete quantum states. Finally, the conclusion and outlook are presented in Section V.

II. EM SYSTEM WITH VECTOR AND SCALAR POTENTIALS

A. **E–B–A– ϕ** Formulas of EM System

The time-harmonic form of Maxwell's equations in linear, isotropic, and nonmagnetic medium can be written as

$$-j\omega\mathbf{B}(\mathbf{r}) = \nabla \times \mathbf{E}(\mathbf{r}) \quad (1)$$

$$j\omega\mathbf{D}(\mathbf{r}) + \mathbf{J}(\mathbf{r}) = \nabla \times \mathbf{H}(\mathbf{r}) \quad (2)$$

$$\nabla \cdot \mathbf{B}(\mathbf{r}) = 0 \quad (3)$$

$$\nabla \cdot \mathbf{D}(\mathbf{r}) = \rho(\mathbf{r}). \quad (4)$$

The constitutive relations between these field components are to be described by

$$\mathbf{D}(\mathbf{r}, \omega) = \varepsilon(\mathbf{r}, \omega)\mathbf{E}(\mathbf{r}, \omega), \mathbf{B}(\mathbf{r}, \omega) = \mu\mathbf{H}(\mathbf{r}, \omega) \quad (5)$$

where $\varepsilon(\mathbf{r}, \omega)$ is the inhomogeneous permittivity of the dispersive medium and μ is the constant permeability.

According to the above constitutive relations, (2) is rewritten as

$$j\omega\varepsilon(\mathbf{r})\mathbf{E}(\mathbf{r}) + \mathbf{J}(\mathbf{r}) = \mu^{-1}\nabla \times \mathbf{B}(\mathbf{r}). \quad (6)$$

By using the divergence-free condition $\nabla \cdot \mathbf{B} = 0$, one can introduce the vector potential **A** through

$$\mathbf{B}(\mathbf{r}) = \nabla \times \mathbf{A}(\mathbf{r}). \quad (7)$$

Using (1), the relation among **A**, ϕ , and **E** satisfies the following:

$$j\omega\mathbf{A}(\mathbf{r}) = -\mathbf{E}(\mathbf{r}) - \nabla\phi(\mathbf{r}). \quad (8)$$

Substituting (8) into (4), we have

$$j\omega\nabla \cdot (\varepsilon(\mathbf{r})\mathbf{A}(\mathbf{r})) + \nabla \cdot (\varepsilon(\mathbf{r})\nabla\phi(\mathbf{r})) = -\rho(\mathbf{r}). \quad (9)$$

Similarly, substituting (7) and (8) into (2), then

$$\mu^{-1}\nabla \times \nabla \times \mathbf{A}(\mathbf{r}) + (j\omega)^2\varepsilon(\mathbf{r})\mathbf{A}(\mathbf{r}) + j\omega\varepsilon(\mathbf{r})\nabla\phi(\mathbf{r}) = \mathbf{J}(\mathbf{r}). \quad (10)$$

To derive the decoupled **A– ϕ** formulas, one method is to use the simple Lorenz gauge

$$\nabla \cdot \mathbf{A}(\mathbf{r}) = -\mu\varepsilon j\omega\phi(\mathbf{r}). \quad (11)$$

It is easy to prove using (11) that the coupled **A– ϕ** formulas can be decoupled in homogeneous media ($\varepsilon(\mathbf{r}) = \varepsilon$)

$$\nabla^2\phi - \mu\varepsilon(j\omega)^2\phi = -\rho/\varepsilon \quad (12)$$

$$\nabla^2\mathbf{A} - \mu\varepsilon(j\omega)^2\mathbf{A} = -\mu\mathbf{J}. \quad (13)$$

Another gauge is the generalized Lorenz gauge [23]

$$\varepsilon(\mathbf{r})^{-1}\nabla \cdot (\varepsilon(\mathbf{r})\mathbf{A}(\mathbf{r})) = -\mu\varepsilon(\mathbf{r})j\omega\phi(\mathbf{r}). \quad (14)$$

The generalized Lorenz gauge defined by (14) can lead to the decoupled **A– ϕ** formulas in inhomogeneous media [14], i.e.,

$$\nabla \cdot (\varepsilon(\mathbf{r})\nabla\phi(\mathbf{r})) - \mu\varepsilon(\mathbf{r})^2(j\omega)^2\phi(\mathbf{r}) = -\rho \quad (15)$$

$$-\mathbf{J} = -\mu^{-1}\nabla \times \nabla \times \mathbf{A}(\mathbf{r}) - (j\omega)^2\varepsilon(\mathbf{r})\mathbf{A}(\mathbf{r}) + \mu^{-1}\varepsilon(\mathbf{r})\nabla[\varepsilon(\mathbf{r})^{-2}\nabla \cdot (\varepsilon(\mathbf{r})\mathbf{A}(\mathbf{r}))]. \quad (16)$$

The two sources in the **A– ϕ** formulas are related to the current continuity equation $\nabla \cdot \mathbf{J} + j\omega\rho = 0$. In order to get the solution of the decoupled **A– ϕ** formulas (12) and (13) or (15) and (16), one needs to numerically solve the second-order partial differential equations (PDEs), which is usually time-consuming and complicated when the FDTD method is applied in time domain.

Instead of directly solving the formulas (12) and (13) or (15) and (16), a novel iteration approach based on the

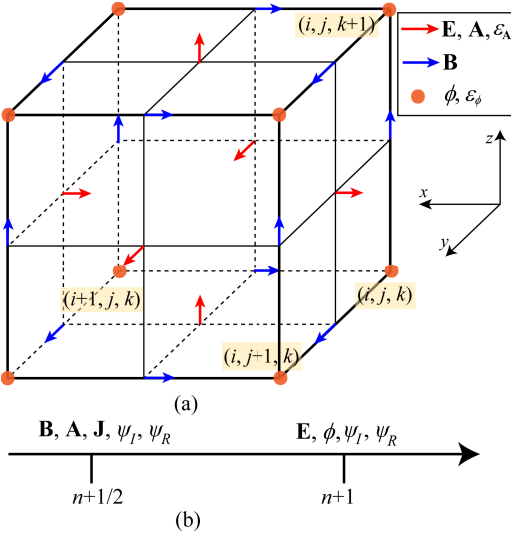


Fig. 1. Space and time configurations of the field components (\mathbf{E} , \mathbf{B} , \mathbf{A} , \mathbf{J} , ϕ , ψ_R , and ψ_I) on a Yee grid indexed as $(i, j, \text{and } k)$ and $n+1/2$ and $n+1$ indicate the points on the time axis.

$\mathbf{E}\text{-}\mathbf{B}\text{-}\mathbf{A}\text{-}\phi$ formulas is proposed to simulate a series of first-order PDEs in sequence. As a result, the $\mathbf{E}\text{-}\mathbf{B}\text{-}\mathbf{A}\text{-}\phi$ formulas can be implemented much more efficiently, particularly for the implementation of PML. Moreover, the gauge condition (11) or (14) can be conveniently adopted to prove the gauge invariance as well. According to the relation between EM field components and potential field components, (6)–(8) can be coupled via the Lorenz gauge condition (11) or (14) to form a self-consistent numerical system, where only first-order PDEs are to be discretized.

To numerically solve the self-consistent system, i.e., (6–8, 11) or (6–8, 14), we can transform the time-harmonic form of the $\mathbf{E}\text{-}\mathbf{B}\text{-}\mathbf{A}\text{-}\phi$ formulas into corresponding time-domain form, which could be easily simulated with the FDTD method. It is shown that the complexity of the proposed $\mathbf{E}\text{-}\mathbf{B}\text{-}\mathbf{A}\text{-}\phi$ formulas is about 1.5 times larger than that of the traditional $\mathbf{E}\text{-}\mathbf{H}$ curl equations.

In the Yee grid of the FDTD method, the electric fields are located at the centers of its edges, and magnetic fields are located at the centers of its faces, as shown in Fig. 1. In our $\mathbf{E}\text{-}\mathbf{B}\text{-}\mathbf{A}\text{-}\phi$ framework, \mathbf{A} and \mathbf{E} are placed at the same positions. According to the Lorenz gauge, the positions of \mathbf{A} and ϕ are half a grid apart, and thus, ϕ is located at the corner of the Yee cell. It must be noted that, for the generalized Lorenz gauge, the location of permittivity $\varepsilon(\mathbf{r})$ on the left-hand side of (14) should be the same as that of \mathbf{A} . Similarly, the location of the permittivity $\varepsilon(\mathbf{r})$ on the right-hand side of (14) should be the same as that of ϕ . The discrete spatial positions of these field components in a Yee cell are shown in Fig. 1.

The time-evolution procedure of the $\mathbf{E}\text{-}\mathbf{B}\text{-}\mathbf{A}\text{-}\phi$ framework is shown in Fig. 2. First, one sets the simulation domain and defines the object in space. Subsequently, in order to reduce the simulation time, some time-independent coefficients are evaluated before starting the time-evaluation loop. At each iteration step, the \mathbf{B} components are calculated by using the value of \mathbf{A} , and then, the value of \mathbf{B} is used to update \mathbf{E} .

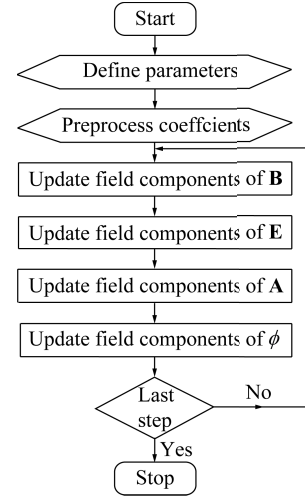


Fig. 2. Schematic of the numerical method for updating the field components in the $\mathbf{E}\text{-}\mathbf{B}\text{-}\mathbf{A}\text{-}\phi$ system.

Using the values of \mathbf{E} and ϕ , the components of \mathbf{A} are evaluated, and then, the corresponding results are used to update the value of ϕ . Simultaneously, the updating equations of the proposed $\mathbf{E}\text{-}\mathbf{B}\text{-}\mathbf{A}\text{-}\phi$ framework are described in detail in the Appendix.

B. CPML for the Proposed EM System

In addition, to numerically simulate the wave propagation in infinite space, the CPML technique is adopted in the $\mathbf{E}\text{-}\mathbf{B}\text{-}\mathbf{A}\text{-}\phi$ system. According to the CPML technique, the spatial differential operator ∇ should be modified as

$$\nabla_s = \frac{1}{s_x} \frac{\partial}{\partial x} \mathbf{e}_x + \frac{1}{s_y} \frac{\partial}{\partial y} \mathbf{e}_y + \frac{1}{s_z} \frac{\partial}{\partial z} \mathbf{e}_z \quad (17)$$

where

$$s_u = k_u + \frac{\sigma_u}{\alpha_u + j\omega\varepsilon_0}. \quad (18)$$

The quantity s_u is a coordinate stretched factor, and the subscript $u = x, y, \text{ and } z$. The parameters in the CPML technique are scaling factors with a polynomial profile m , and the specific expressions of these parameters are given in [24].

Using a recursive convolution method, the updating equations of the field components along the x -direction take the following form

$$\varepsilon \frac{\partial E_x}{\partial t} = \frac{1}{k_y} \frac{\partial B_z}{\partial y} - \frac{1}{k_z} \frac{\partial B_y}{\partial z} + \Psi_{Exy} - \Psi_{Exz} \quad (19)$$

$$B_x = \frac{1}{k_y} \frac{\partial A_z}{\partial y} - \frac{1}{k_z} \frac{\partial A_y}{\partial z} + \Psi_{Bxy} - \Psi_{Bxz} \quad (20)$$

$$\frac{\partial A_x}{\partial t} = -\frac{1}{k_x} \frac{\partial \phi}{\partial x} - \Psi_{Axx} - E_x. \quad (21)$$

The formula of the generalized Lorenz gauge in the CPML region can be derived as

$$\frac{\partial \phi}{\partial t} = -\frac{1}{\mu\varepsilon_\phi^2} \left(\frac{1}{k_x} \frac{\partial (\varepsilon_{xA} A_x)}{\partial x} + \frac{1}{k_y} \frac{\partial (\varepsilon_{yA} A_y)}{\partial y} + \frac{1}{k_z} \frac{\partial (\varepsilon_{zA} A_z)}{\partial z} \right) + \Psi_{\phi x} + \Psi_{\phi y} + \Psi_{\phi z}. \quad (22)$$

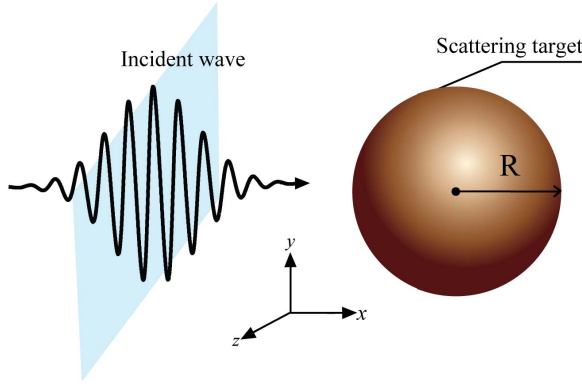


Fig. 3. Dielectric sphere illuminated by an EM plane wave.

The auxiliary variables Ψ in (19)–(22) can be updated by using the corresponding field components. For instance, the auxiliary variable in (22) along the x -direction takes the forms

$$\Psi_{\phi_{x_i,j,k}}^{n+1} = b_x \Psi_{\phi_{x_i,j,k}}^n + c_x \frac{\partial(\epsilon_{xA}A_x)}{\partial x} \quad (23)$$

and

$$b_x = e^{-((\sigma_x/k_x) + \alpha_x)(\Delta t/\epsilon_0)} \quad (24)$$

$$c_x = \frac{\sigma_x}{\sigma_x k_x + \alpha_x k_x^2} (e^{-((\sigma_x/k_x) + \alpha_x)(\Delta t/\epsilon_0)} - 1). \quad (25)$$

It is worth noting that the proposed **E–B–A– ϕ** numerical system should be divided into two parts when operating the CPML parameters: one is the **E–B** and the other is the **A– ϕ** . The settings of the CPML parameters for the field components **E–B** are the same as those of the field components **E–H**. It is known that the CPML parameters for field components **E–H** are defined by their locations in space domain. It can be seen from Fig. 1 that the field components **E** are located at the ends of the edges and the field components **B** are located at the centers of the edges. Therefore, the distance of half a grid between **E** and **B** in each direction should be considered when defining the CPML parameters. Although **A** and **E** are placed at the same positions, however, the field components **A** are located at the centers of the edges and the field components ϕ are located at the ends of the edges in each direction when considering the **A– ϕ** part. Through the above analyses, it is known that the settings of CPML parameters for the field components **A** should be the same as those of the field components **B**. Similarly, the settings of CPML parameters for the field components ϕ should be the same as those of the field components **E**. The validation and flexibility of the proposed method for the CPML technique applied in this EM system have been investigated in the following section.

III. NUMERICAL EXAMPLES FOR EM SYSTEM

The physical system used to verify the accuracy of the proposed numerical method and its gauge invariance is shown in Fig. 3, where a 3-D lossless dielectric sphere with the relative permittivity $\epsilon_r = 4$ is illuminated by a plane-wave excitation. The radius of the sphere is $R = 300$ nm. The Yee grid size is chosen as $\Delta x = \Delta y = \Delta z = \Delta = 15$ nm, and

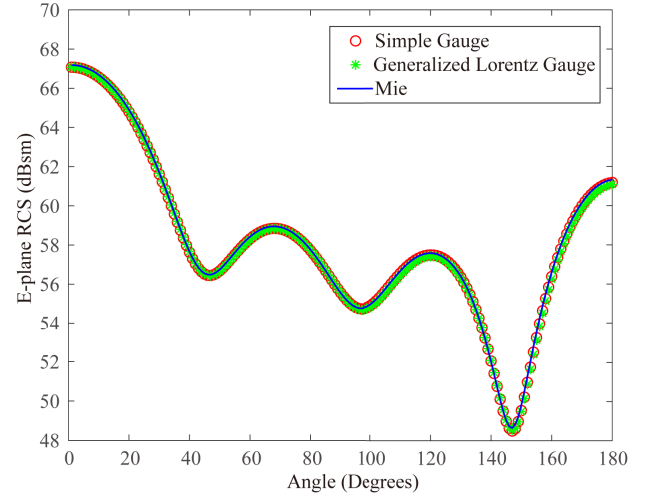


Fig. 4. E-plane bistatic RCS for a lossless dielectric sphere with the size of half wavelength and relative permittivity of 4.

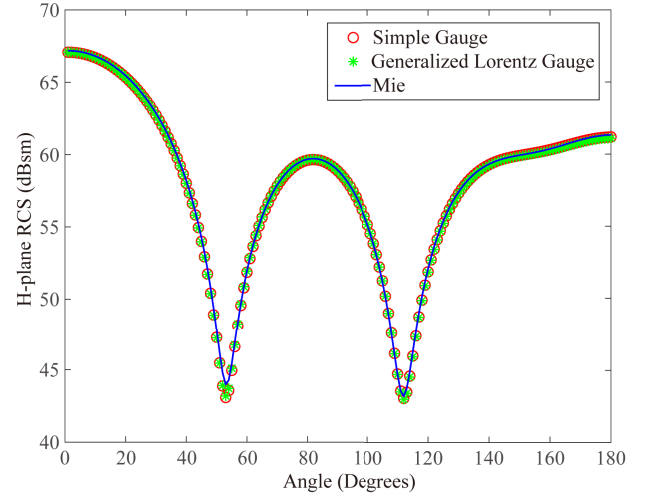


Fig. 5. H-plane bistatic RCS for a lossless dielectric sphere with the size of half wavelength and relative permittivity of 4.

the time step interval equals 0.78 times the CFL maximum allowed time step in the FDTD method. The computational domain is surrounded by 15 layers of CPML and consists of $91 \times 91 \times 91$ grid cells. The parameters in the CPML technique are scaling factors with a polynomial profile m ($m = 1.9$ in this example). The specific expressions of these parameters are given in [24], and the corresponding optimal values are chosen as $k_{\max} = 1$ and $\sigma_{\max} = 0.5(m + 1)/(150\pi \Delta)$. The incident plane wave has a modulated Gaussian envelope in time with a carrier frequency of 500 THz (wavelength of 600 nm) and $t_0 = 3\tau$, $\tau = 1.5$ fs (t_0 denotes the time reaching peak value of the Gaussian pulse). The proposed **A– ϕ** framework is applied to evaluate the bistatic E- and H-plane radar cross section (RCS) at the center frequency. As shown in Figs. 4 and 5, the numerical results of simple gauge and generalized Lorentz gauge ($\epsilon = 4\epsilon_0$) agree well with each other. Moreover, all the numerical results exhibit very high accuracy compared to the analytical results of Mie series solution. Hence, the accuracy of the proposed numerical framework is verified and the gauge invariance of the EM fields is numerically demonstrated.

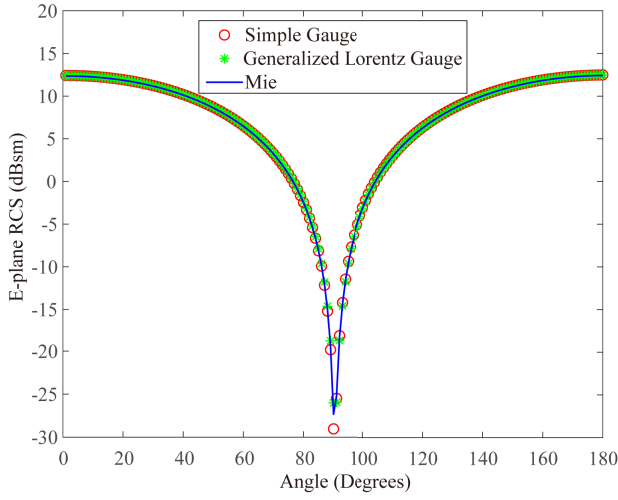


Fig. 6. E-plane bistatic RCS for a dispersive metallic sphere (with the radius of 20 nm and incident wavelength of 600 nm).

To further verify the gauge invariance of the universal $\mathbf{A}-\phi$ formalism, a more complicated 3-D dispersive metallic sphere is studied. The radius of the sphere is 20 nm. The grid size is chosen as $\Delta x = \Delta y = \Delta z = \Delta = 1$ nm, and the time step interval equals 0.61 times the CFL maximum allowed time step in the FDTD method. In this example, the dispersive permittivity of metallic medium is described by the Drude model as

$$\epsilon^{\text{Drude}}(\omega) = \epsilon_0[\epsilon_\infty - \chi(\omega)] = \epsilon_0\epsilon_\infty - \epsilon_0 \frac{\omega_p^2}{\omega(\omega - j\nu_c)} \quad (26)$$

where ϵ_∞ is the relative permittivity at infinitely-large frequencies, ω_p is the plasma frequency, and ν_c is the damping coefficient. Hence, to simulate dispersive media, (6) can be discretized by the auxiliary differential equation (ADE) scheme [25]. In this example, $\epsilon_\infty = 9.5$, $\omega_p = 1.36 \times 10^{16}$ Hz, and $\nu_c = 1.048 \times 10^{15}$ Hz. For simplification, the generalized Lorenz gauge (14) in this example is given by

$$(\epsilon_0\epsilon_\infty)^{-1} \nabla \cdot (\epsilon_0\epsilon_\infty \mathbf{A}) = -\mu_0\epsilon_0\epsilon_\infty j\omega\phi \quad (27)$$

where $\epsilon_\infty = 9.5$ in the sphere region and $\epsilon_\infty = 1$ in the air region. Regarding the simple gauge, $\epsilon_\infty = 1$ is set for all regions.

The bistatic E-plane RCS of the dispersive metallic sphere is given in Fig. 6, whereas the absorbing cross section (ACS) and scattering cross section (SCS) are presented in Figs. 7 and 8, respectively. These simulation comparisons show that the results obtained by the simple gauge agree well with those obtained by the generalized Lorenz gauge. Moreover, both numerical methods agree well with the analytical results.

Meanwhile, the accuracy of the proposed $\mathbf{E}-\mathbf{B}-\mathbf{A}-\phi$ formulas system in simulating the propagation of the EM field and the absorbing performance of the CPML applied in this system are investigated. Considering the radiation of an electric dipole in a three-dimensional space, the vertical dipole is assumed to be at the center of the computational region. The computational region contains $60 \times 60 \times 60$ Yee cells and the cell sizes are chosen as $\Delta x = \Delta y = \Delta z = 0.05$ m. A Gaussian

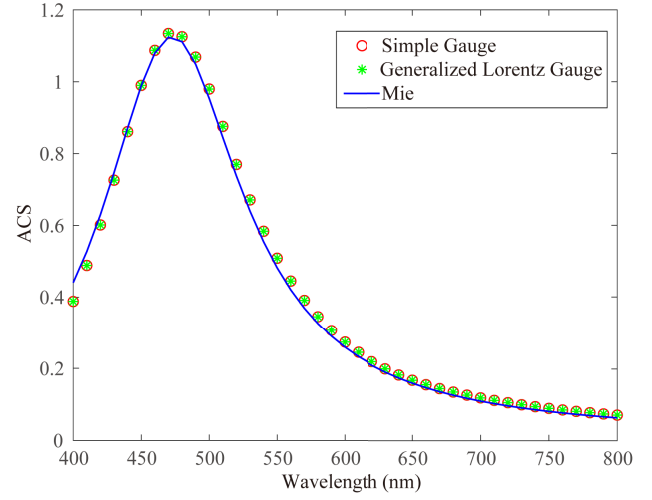


Fig. 7. ACS for a dispersive metallic sphere (with the radius of 20 nm).

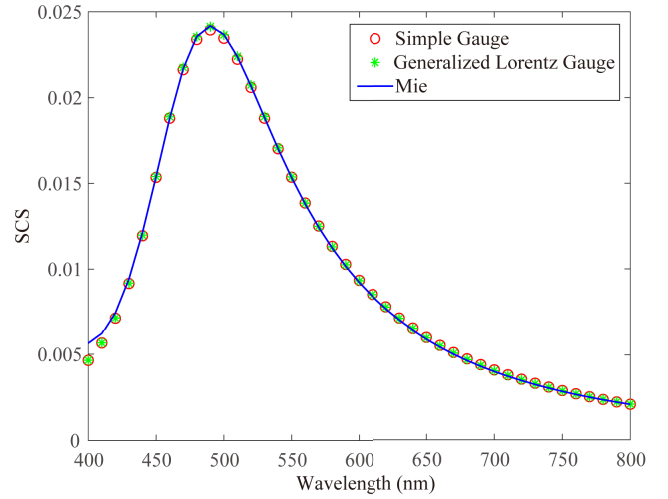


Fig. 8. SCS for a dispersive metallic sphere (with the radius of 20 nm).

source with a time-domain form of $e^{((t-3\tau)/\tau)^2}$ ($\tau = 2$ ns) is used as the radiation source and the probe point is placed two cells away from the interface between the computational domain and the CPML region. The number of the CPML layers is 10 and the parameters are chosen as $m = 3$, $\alpha_{\max} = 0.04(m+1)/(150\pi\Delta)$, $\sigma_{\max} = 0.5(m+1)/(150\pi\Delta)$, and $k_{\max} = 1$. The radiation results of the electric dipole are shown in Fig. 9. For comparison, the numerical results obtained by using the traditional $\mathbf{E}-\mathbf{H}$ Maxwell equations (1) and (2), $\mathbf{A}-\phi$ framework (12) and (13), and the proposed $\mathbf{E}-\mathbf{B}-\mathbf{A}-\phi$ system are provided. It can be seen that the result obtained by the proposed system has a good agreement with that obtained by the traditional $\mathbf{E}-\mathbf{H}$ and $\mathbf{A}-\phi$ frameworks. Therefore, the accuracy of the proposed system in simulating the propagation of the EM field is demonstrated.

To evaluate the absorbing performance of the CPML applied in this $\mathbf{E}-\mathbf{B}-\mathbf{A}-\phi$ system, the relative reflection errors at the probe point are calculated by the following:

$$E_{\text{error}} = 20 \log_{10} \frac{|E(t) - E_{\text{ref}}(t)|}{\max_t |E_{\text{ref}}(t)|} \quad (28)$$

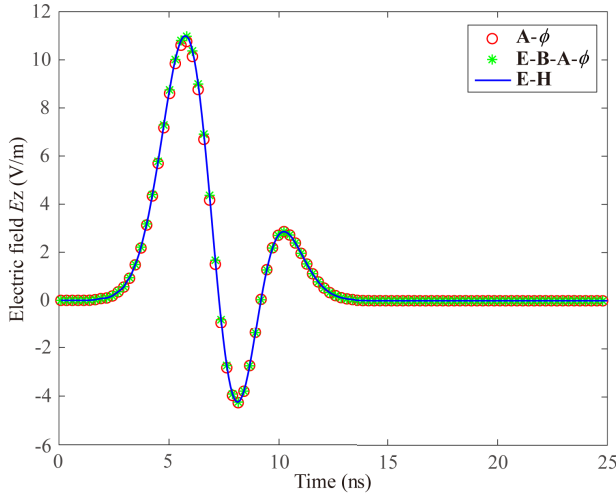


Fig. 9. Radiation field of electric dipole for the $\mathbf{A}-\phi$, $\mathbf{E}-\mathbf{B}-\mathbf{A}-\phi$, and $\mathbf{E}-\mathbf{H}$ system.

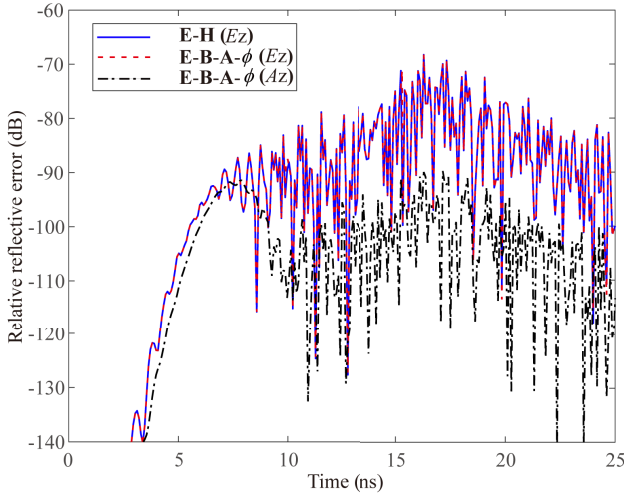


Fig. 10. Relative reflection errors of the probe point E_z for the $\mathbf{E}-\mathbf{B}-\mathbf{A}-\phi$ system and $\mathbf{E}-\mathbf{H}$ system, and the probe point A_z for the $\mathbf{E}-\mathbf{B}-\mathbf{A}-\phi$ system.

where $E(t)$ denotes the field component at the probe point and $E_{\text{ref}}(t)$ is the reference field value at the point within an enlarged simulation domain where there are no reflected EM waves.

As shown in Fig. 10, for the E_z field component at the probe point, both the proposed $\mathbf{E}-\mathbf{B}-\mathbf{A}-\phi$ numerical system and traditional $\mathbf{E}-\mathbf{H}$ numerical system have the comparable relative reflection error and the maximum value is around -70 dB. In addition, the relative reflection errors of the proposed $\mathbf{E}-\mathbf{B}-\mathbf{A}-\phi$ numerical system for the A_z field component at the probe point are also investigated, and the maximum value is around -90 dB. These results demonstrate the validation and efficiency of applying the CPML technique to the proposed system.

IV. MAXWELL-SCHRÖDINGER SYSTEM

The progress of laser technology enables the control of quantum states of the electron. The problems of realizing the perfect switching of quantum states have attracted increasing interest over the past two decades. As mentioned in Section I,

scientists have conducted extensive research on controlling the quantum states of a single electron by solving the semi-classical M-S equations with the FDTD solver. In addition, various forms of Maxwell's equations based on the \mathbf{A} and ϕ formulas are derived and are to be coupled to the Schrödinger equation. The \mathbf{A} and ϕ formulas introduced in the literature contain second-order partial differential operators, and thus, the corresponding simulation is usually time-consuming and complicated. Due to the simplicity of the proposed $\mathbf{E}-\mathbf{B}-\mathbf{A}-\phi$ equations, these EM equations are coupled to the following Schrödinger (29) and the quantum current density (30) to analyze the transient interaction between the incident EM field and the electron

$$i\hbar \frac{\partial}{\partial t} \psi(\mathbf{r}, t) = \left[-\frac{\hbar^2}{2m_0} \nabla^2 + \frac{ie\hbar}{m_0} \mathbf{A} \cdot \nabla + \frac{ie\hbar}{2m_0} (\nabla \cdot \mathbf{A}) + e\phi + V + \frac{e^2}{2m_0} \mathbf{A}^2 \right] \psi(\mathbf{r}, t) \quad (29)$$

$$\mathbf{J}(\mathbf{r}, t) = \frac{-ie\hbar}{2m_0} [\psi^*(\mathbf{r}, t) \nabla \psi(\mathbf{r}, t) - \psi(\mathbf{r}, t) \nabla \psi^*(\mathbf{r}, t)] - \frac{e^2}{m_0} \psi^*(\mathbf{r}, t) \mathbf{A} \psi(\mathbf{r}, t) \quad (30)$$

where \hbar is the reduced Planck's constant, e and m_0 are the charge and mass of the electron, respectively, V is the electrostatic quantum confinement potential, and ψ is the wave function of the particle.

Meanwhile, the complex-valued calculations for solving (29) can be simplified to real-valued calculations via splitting the wave function into its real and imaginary parts

$$\psi(\mathbf{r}, t) = \psi_R(\mathbf{r}, t) + i\psi_I(\mathbf{r}, t). \quad (31)$$

In addition, as for the model shown in Fig. 1, the time-dependent wave function of this electron confined in a quasi-one-dimensional potential V and subjected to a radiation field with ϕ and A_z .

Therefore, (29) can be derived as

$$\begin{aligned} \frac{\partial}{\partial t} \psi_I(\mathbf{r}, t) &= \frac{\hbar}{2m_0} \nabla^2 \psi_R(\mathbf{r}, t) + \frac{e}{m_0} \mathbf{A}_z \cdot \nabla \psi_I(\mathbf{r}, t) \\ &+ \frac{e}{2m_0} (\nabla \cdot \mathbf{A}_z) \psi_I(\mathbf{r}, t) - \left(\frac{e\phi + V}{\hbar} + \frac{e^2}{2m_0 \hbar} \mathbf{A}_z^2 \right) \psi_R(\mathbf{r}, t) \end{aligned} \quad (32)$$

$$\begin{aligned} \frac{\partial}{\partial t} \psi_R(\mathbf{r}, t) &= -\frac{\hbar}{2m_0} \nabla^2 \psi_I(\mathbf{r}, t) + \frac{e}{m_0} \mathbf{A}_z \cdot \nabla \psi_R(\mathbf{r}, t) \\ &+ \frac{e}{2m_0} (\nabla \cdot \mathbf{A}_z) \psi_R(\mathbf{r}, t) + \left(\frac{e\phi + V}{\hbar} + \frac{e^2}{2m_0 \hbar} \mathbf{A}_z^2 \right) \psi_I(\mathbf{r}, t) \end{aligned} \quad (33)$$

and the polarization current (30) density is thus obtained

$$\begin{aligned} J_z(\mathbf{r}, t) &= \frac{e\hbar}{2m_0} [\psi_R(\mathbf{r}, t) \nabla \psi_I(\mathbf{r}, t) - \psi_I(\mathbf{r}, t) \nabla \psi_R(\mathbf{r}, t)] \\ &- \frac{e^2}{m_0} (\psi_R^2(\mathbf{r}, t) + \psi_I^2(\mathbf{r}, t)) A_z. \end{aligned} \quad (34)$$

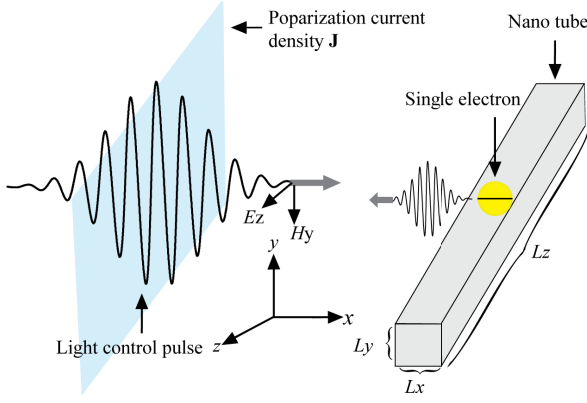


Fig. 11. Geometric model of a nanotube.

According to (32) and (33), we can see that the real and imaginary parts of wave function ($\psi_I(\mathbf{r}, t)$, $\psi_R(\mathbf{r}, t)$) appear at both sides of (32) and (33), respectively. Thus, the wave function should be sampled at the time steps of $n + 1$ and $n + 1/2$ when (32) and (33) are discretized as the discrete forms. Accordingly, two sets of iterative equations are constructed. The first group is used to solve the wave function at the time step of $n + 1/2$, and the second group is used to solve the wave function at the time step of $n + 1$, as shown in Fig. 1. The updating formulas for (32)–(34) are described in detail in the Appendix.

According to the theory of [20], the control pulse generator is designed to maximize the objective state ψ_1 of the electron from the ground state ψ_0 . The control pulse E^s can be generated by solving the following:

$$E^s = -2 \frac{E_0}{m_0} \text{Im} \langle \psi' | W e z | \psi' \rangle \quad (35)$$

where W represents the projection operator of $|\psi_1\rangle\langle\psi_1|$ and $\psi' = e^{[-i(e/\hbar)A_z(z,t)]}\psi$ is a unitary transformation for the wave function ψ , and the derivation of (35) is introduced in [26]–[28]. At last, applying equations EM (6)–(8) and (11), Schrödinger (32) and (33), polarization current density (34), and the control pulse E^s (35), the proposed scheme can provide a numerical simulation (as shown in Fig. 11), where a uniform plane-wave source excites the electrons in a nanotube to transform the quantum states of the electron from the ground state ψ_0 to the first excited state ψ_1 .

Fig. 12 shows a procedure illustration of the proposed method for updating the field components in the coupled M–S system. First, the control pulse E^s (35) is obtained by the wave function of the electron, and the polarization current density J_z (34) generated by the electron motion will generate the radiation fields governed by the EM system [see (6)–(8) and (11)]. Then, the radiation fields will superimpose with the control pulse field E^s as the total external EM field acting on the quantum system governed by (32) and (33), and thus, the steps of transforming the control pulse E^s to A^s and then superimpose with A_z are added in multiphysics simulation, as shown in Fig. 12. Although the incident EM field is polarized along the z -axis having thus only E_z and B_y components initially, the last field components are also needed

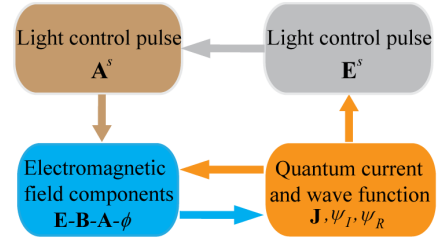
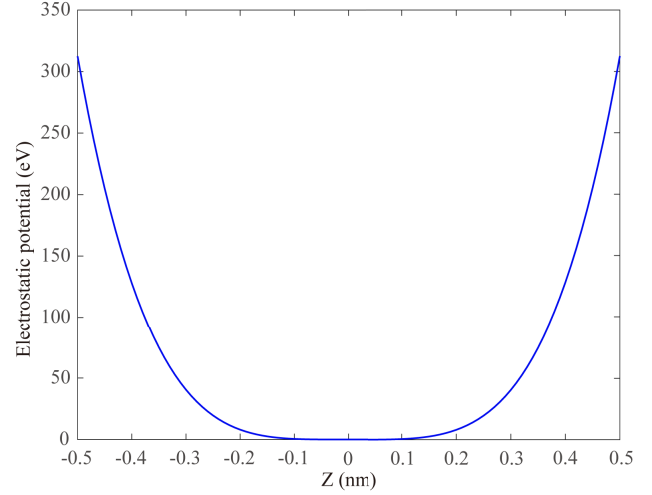


Fig. 12. Procedure illustration of the proposed method for updating the field components in the coupled M–S system.

Fig. 13. Confining potential V along the z -direction.

to interact with the electron. Therefore, all the fields, including A_x , A_y , A_z , ϕ , E_x , E_y , E_z , B_x , B_y , and B_z , are updated in every iteration.

Finally, according to the program diagram of Fig. 12, the numerical multiphysics simulation is performed. For the EM system, the computational region contains $50 \times 50 \times 120$ Yee cells with the CPML region of ten layers, and the cell sizes are chosen as $\Delta x = \Delta y = 1$ nm and $\Delta z = 0.01$ nm. For the QM system, as the electron is confined in the quasi-one-dimensional space extending along the z -axis like a “tube,” its wave function is dependent only on the z -coordinate. In other directions, the wave function is set to be uniform and the value is not zero only within one unit Δx and Δy of the Yee cell. Hence, the wave function is norm normalized as

$$\Delta x \Delta y \int_{-\infty}^{\infty} |\psi(z)|^2 dz = 1 \quad (36)$$

and the length of the nanotube along the z -direction is chosen as 1 nm; thus, 100 Yee cells are included in the QM system along the z -direction.

The ground state ψ_0 and the excited state ψ_1 with the confining potential V (Fig. 13) are shown in Fig. 14. For numerical convergence, the wave function is initialized to be as

$$\psi = \sqrt{0.9999} \psi_0 + \sqrt{0.0001} \psi_1. \quad (37)$$

As shown in Fig. 15, the electron wave packet $|\psi|^2$ initially exists as a single peak, which corresponds to the ground state

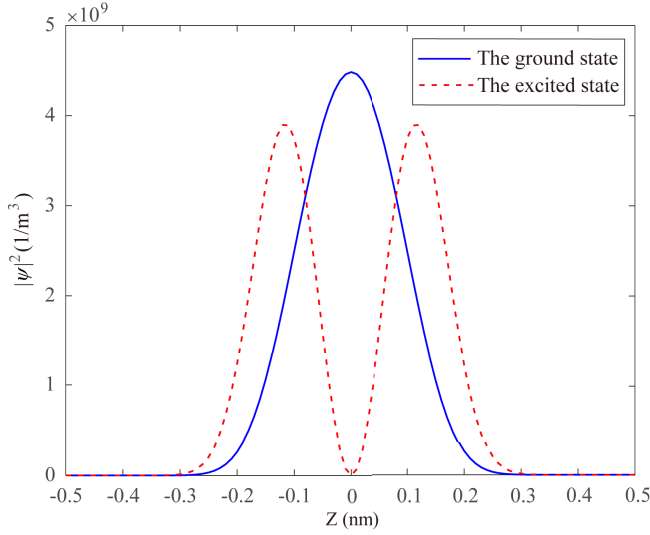


Fig. 14. Electron wave packet distribution of the ground state and the excited state. The corresponding eigenenergies are 2.05 and 7.35 eV, respectively.

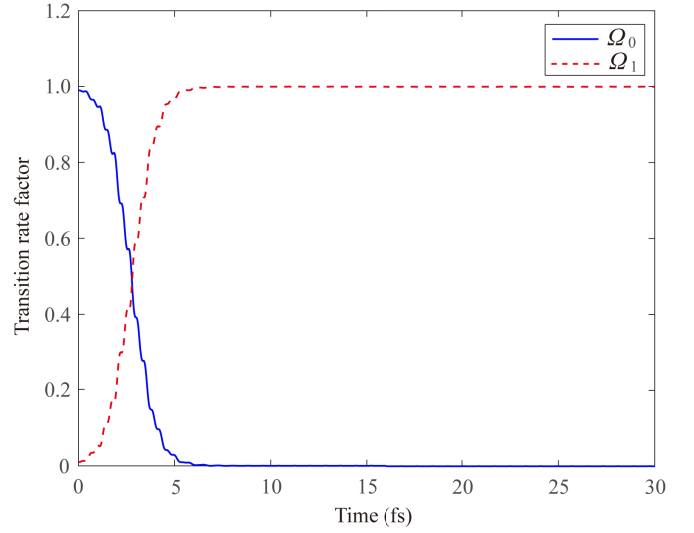


Fig. 16. Magnitude of the transition rate factor Ω .

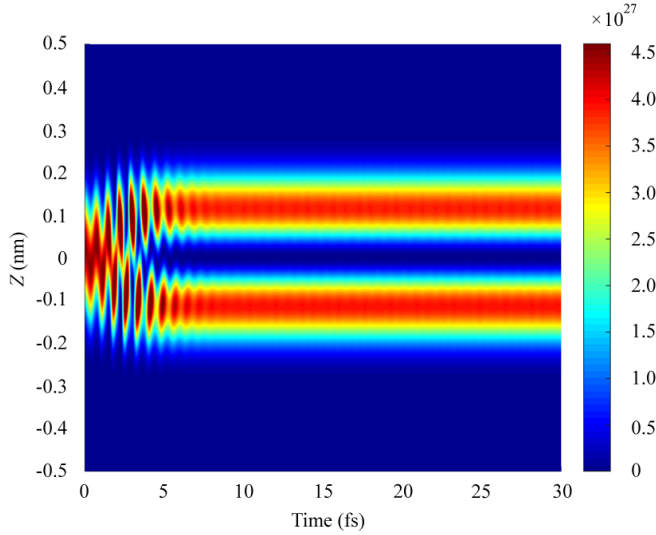


Fig. 15. Spatiotemporal plots of the probability density $|\psi|^2$.

of the electron, and then, the electron wave packet starts fluctuating about the time 2 fs. During the time interval of 2–10 fs, the electron wave packet oscillates rapidly under the illumination of the pulse and is finally converted into the bimodal form, which corresponds to the first excited state of the electron. In addition, to quantify the quantum state transition by the proposed scheme, the transition rate factor Ω_k is defined as

$$\Omega_k = \langle \psi' | \psi_k \rangle \langle \psi_k | \psi' \rangle \quad (38)$$

where ψ_k denotes the quantum state of the electron. The resultant variations of the factors are shown in Fig. 16. As the simulation time increases, the factor Ω_0 decreases from one to zero and the factor Ω_1 increases from zero to one when the pulse gradually raises ($t = 3$ –10 fs). Finally, the value of factor Ω_1 remains stable when the pulse has gone. It can

be concluded that the perfect quantum state transition is numerically achieved by using the proposed M–S system.

V. CONCLUSION

Universal vector–scalar potentials system is proposed to model the EM response from arbitrary inhomogeneous media and demonstrate the gauge invariance. The numerical results show that both simple gauge and generalized Lorenz gauge can be adopted to calculate the time evolution of EM fields in dispersive and nondispersive inhomogeneous media, and the results obtained by the two gauges are nearly identical. In view of simplicity and stability, the simple gauge is suggested to be used. Moreover, the method of applying the CPML technique to the proposed system is introduced, and the numerical results demonstrate the validation and efficiency of the CPML technique.

In addition, the proposed method provides a convenient way to calculate the vector and scalar potentials, which is essential to model the semiclassical quantum EM problems described by the M–S equations. The combination of the proposed EM system with the Schrödinger equation is presented to design laser pulse for controlling discrete quantum states. The simulation results show that the proposed method reproduces a perfect quantum state switching while with a more straightforward numerical solution process. In future, the proposed numerical method will be used to manipulate the discrete multiquantum states and other multiphysics problems in more complex environments where irregular structures are included.

APPENDIX

For the EM part, according to the spatial and temporal configuration of the field components as shown in Fig. 1, the symbols i , j , and k denote spatial coordinates, while n denotes the sampling point in time domain. Then, according to the time-evolution procedure of the **E–B–A– ϕ** framework as shown in Fig. 2, the updating equations for the

EM framework are expressed as (39)–(44), shown at the bottom of the page, where m denotes $(i + (1/2), j, k)$, $(i, j + (1/2), k)$, and $(i, j, k + (1/2))$, respectively, and

$$CA(m) = \left(1 - \frac{\sigma(m)\Delta t}{2\varepsilon(m)}\right) / \left(1 + \frac{\sigma(m)\Delta t}{2\varepsilon(m)}\right) \quad (45)$$

$$CB(m) = \frac{\Delta t}{\varepsilon(m)} / \left(1 + \frac{\sigma(m)\Delta t}{2\varepsilon(m)}\right). \quad (46)$$

For the scalar potential \mathbf{A} and ϕ , we have

$$\begin{aligned} A_x^{n+\frac{1}{2}}\left(i + \frac{1}{2}, j, k\right) &= A_x^{n-\frac{1}{2}}\left(i + \frac{1}{2}, j, k\right) - \Delta t E_x^n\left(i + \frac{1}{2}, j, k\right) \\ &\quad - \frac{\Delta t}{\Delta x} [\phi^n(i + 1, j, k) - \phi^n(i, j, k)] \end{aligned} \quad (47)$$

$$\begin{aligned} A_y^{n+\frac{1}{2}}\left(i, j + \frac{1}{2}, k\right) &= A_y^{n-\frac{1}{2}}\left(i, j + \frac{1}{2}, k\right) - \Delta t E_y^n\left(i, j + \frac{1}{2}, k\right) \\ &\quad - \frac{\Delta t}{\Delta y} [\phi^n(i, j + 1, k) - \phi^n(i, j, k)] \end{aligned} \quad (48)$$

$$\begin{aligned} A_z^{n+\frac{1}{2}}\left(i, j, k + \frac{1}{2}\right) &= A_z^{n-\frac{1}{2}}\left(i, j, k + \frac{1}{2}\right) - \Delta t E_z^n\left(i, j, k + \frac{1}{2}\right) \\ &\quad - \frac{\Delta t}{\Delta z} [\phi^n(i, j, k + 1) - \phi^n(i, j, k)] \end{aligned} \quad (49)$$

$$\begin{aligned} \phi^{n+1}(i, j, k) &= \phi^n(i, j, k) - \frac{\Delta t}{\mu_0 \varepsilon_\phi^2} \\ &\quad \times \left\{ \frac{1}{\Delta x} \varepsilon_{A_x}\left(i + \frac{1}{2}, j, k\right) \left[A_x^{n+\frac{1}{2}}\left(i + \frac{1}{2}, j, k\right) - A_x^{n+\frac{1}{2}}\left(i - \frac{1}{2}, j, k\right) \right] \right. \\ &\quad + \frac{1}{\Delta y} \varepsilon_{A_y}\left(i, j + \frac{1}{2}, k\right) \left[A_y^{n+\frac{1}{2}}\left(i, j + \frac{1}{2}, k\right) - A_y^{n+\frac{1}{2}}\left(i, j - \frac{1}{2}, k\right) \right] \\ &\quad + \frac{1}{\Delta z} \varepsilon_{A_z}\left(i, j, k + \frac{1}{2}\right) \left[A_z^{n+\frac{1}{2}}\left(i, j, k + \frac{1}{2}\right) - A_z^{n+\frac{1}{2}}\left(i, j, k - \frac{1}{2}\right) \right] \left. \right\}. \end{aligned} \quad (50)$$

$$\begin{aligned} B_x^{n+\frac{1}{2}}\left(i, j + \frac{1}{2}, k + \frac{1}{2}\right) &= \frac{1}{\Delta y} \left(A_z^{n+\frac{1}{2}}\left(i, j + 1, k + \frac{1}{2}\right) - A_z^{n+\frac{1}{2}}\left(i, j, k + \frac{1}{2}\right) \right) \\ &\quad - \frac{1}{\Delta z} \left(A_y^{n+\frac{1}{2}}\left(i, j + \frac{1}{2}, k + 1\right) - A_y^{n+\frac{1}{2}}\left(i, j + \frac{1}{2}, k\right) \right) \end{aligned} \quad (39)$$

$$\begin{aligned} B_y^{n+\frac{1}{2}}\left(i + \frac{1}{2}, j, k + \frac{1}{2}\right) &= \frac{1}{\Delta z} \left(A_x^{n+\frac{1}{2}}\left(i + \frac{1}{2}, j, k + 1\right) - A_x^{n+\frac{1}{2}}\left(i + \frac{1}{2}, j, k\right) \right) \\ &\quad - \frac{1}{\Delta x} \left(A_z^{n+\frac{1}{2}}\left(i + 1, j, k + \frac{1}{2}\right) - A_z^{n+\frac{1}{2}}\left(i, j, k + \frac{1}{2}\right) \right) \end{aligned} \quad (40)$$

$$\begin{aligned} B_z^{n+\frac{1}{2}}\left(i + \frac{1}{2}, j + \frac{1}{2}, k\right) &= \frac{1}{\Delta x} \left(A_y^{n+\frac{1}{2}}\left(i + 1, j + \frac{1}{2}, k\right) - A_y^{n+\frac{1}{2}}\left(i, j + \frac{1}{2}, k\right) \right) \\ &\quad - \frac{1}{\Delta y} \left(A_x^{n+\frac{1}{2}}\left(i + \frac{1}{2}, j + 1, k\right) - A_x^{n+\frac{1}{2}}\left(i + \frac{1}{2}, j, k\right) \right) \end{aligned} \quad (41)$$

$$\begin{aligned} E_x^{n+1}\left(i + \frac{1}{2}, j, k\right) &= CA(m) E_x^n\left(i + \frac{1}{2}, j, k\right) + CB(m) \\ &\quad \times \left[\left(B_z^{n+1/2}\left(i + \frac{1}{2}, j + \frac{1}{2}, k\right) - B_z^{n+1/2}\left(i + \frac{1}{2}, j - \frac{1}{2}, k\right) \right) / \Delta y \right. \\ &\quad \left. - \left(B_y^{n+1/2}\left(i + \frac{1}{2}, j, k + \frac{1}{2}\right) - B_y^{n+1/2}\left(i + \frac{1}{2}, j, k - \frac{1}{2}\right) \right) / \Delta z \right] \end{aligned} \quad (42)$$

$$\begin{aligned} E_y^{n+1}\left(i, j + \frac{1}{2}, k\right) &= CA(m) \cdot E_y^{n+1}\left(i, j + \frac{1}{2}, k\right) + CB(m) \\ &\quad \times \left[\left(B_x^{n+1/2}\left(i, j + \frac{1}{2}, k + \frac{1}{2}\right) - B_x^{n+1/2}\left(i, j + \frac{1}{2}, k - \frac{1}{2}\right) \right) / \Delta z \right. \\ &\quad \left. - \left(B_z^{n+1/2}\left(i + \frac{1}{2}, j + \frac{1}{2}, k\right) - B_z^{n+1/2}\left(i - \frac{1}{2}, j + \frac{1}{2}, k\right) \right) / \Delta x \right] \end{aligned} \quad (43)$$

$$\begin{aligned} E_z^{n+1}\left(i, j, k + \frac{1}{2}\right) &= CA(m) \cdot E_z^{n+1}\left(i, j, k + \frac{1}{2}\right) + CB(m) \\ &\quad \times \left[\left(B_y^{n+1/2}\left(i + \frac{1}{2}, j, k + \frac{1}{2}\right) - B_y^{n+1/2}\left(i - \frac{1}{2}, j, k + \frac{1}{2}\right) \right) / \Delta x \right. \\ &\quad \left. - \left(B_x^{n+1/2}\left(i, j + \frac{1}{2}, k + \frac{1}{2}\right) - B_x^{n+1/2}\left(i, j - \frac{1}{2}, k + \frac{1}{2}\right) \right) / \Delta y \right] \end{aligned} \quad (44)$$

For the QM part, the updating equations for the discrete forms of (32)–(34) are expressed as

$$\begin{aligned} \psi_R^{n+\frac{1}{2}}(k) &= \psi_R^{n-\frac{1}{2}}(k) - \frac{\Delta t \hbar}{2m_0} \alpha [\psi_I^n(k)] \\ &+ \frac{\Delta te}{m_0} A_z^n(k) \beta [\psi_R^n(k)] + \frac{\Delta te}{2m_0} \beta [A_z^n(k)] \psi_R^n(k) \\ &+ \left(\frac{\Delta te^2}{2m_0 \hbar} (A_z^n(k))^2 + \frac{\Delta t V(k)}{\hbar} + \frac{\Delta te \phi^n(k)}{\hbar} \right) \psi_I^n(k) \end{aligned} \quad (51)$$

$$\begin{aligned} \psi_I^{n+\frac{1}{2}}(k) &= \psi_I^{n-\frac{1}{2}}(k) + \frac{\Delta t \hbar}{2m_0} \alpha [\psi_R^n(k)] \\ &+ \frac{\Delta te}{m_0} A_z^n(k) \beta [\psi_I^n(k)] + \frac{\Delta te}{2m_0} \beta [A_z^n(k)] \psi_I^n(k) \\ &- \left(\frac{\Delta te^2}{2m_0 \hbar} (A_z^n(k))^2 + \frac{\Delta t V(k)}{\hbar} + \frac{\Delta te \phi^n(k)}{\hbar} \right) \psi_R^n(k) \end{aligned} \quad (52)$$

$$\begin{aligned} \psi_R^{n+1}(k) &= \psi_R^n(k) - \frac{\Delta t \hbar}{2m_0} \alpha [\psi_I^{n+\frac{1}{2}}(k)] \\ &+ \frac{\Delta te}{m_0} A_z^{n+\frac{1}{2}}(k) \beta [\psi_R^{n+\frac{1}{2}}(k)] + \frac{\Delta te}{2m_0} \beta [A_z^{n+\frac{1}{2}}(k)] \psi_R^{n+\frac{1}{2}}(k) \\ &+ \left(\frac{\Delta te^2}{2m_0 \hbar} (A_z^{n+\frac{1}{2}}(k))^2 + \frac{\Delta t V(k)}{\hbar} + \frac{\Delta te \phi^{n+\frac{1}{2}}(k)}{\hbar} \right) \psi_I^{n+\frac{1}{2}}(k) \end{aligned} \quad (53)$$

$$\begin{aligned} \psi_I^{n+1}(k) &= \psi_I^n(k) + \frac{\Delta t \hbar}{2m_0} \alpha [\psi_R^{n+\frac{1}{2}}(k)] \\ &+ \frac{\Delta te}{m_0} A_z^{n+\frac{1}{2}}(k) \beta [\psi_I^{n+\frac{1}{2}}(k)] + \frac{\Delta te}{2m_0} \beta [A_z^{n+\frac{1}{2}}(k)] \psi_I^{n+\frac{1}{2}}(k) \\ &- \left(\frac{\Delta te^2}{2m_0 \hbar} (A_z^{n+\frac{1}{2}}(k))^2 + \frac{\Delta t V(k)}{\hbar} + \frac{\Delta te \phi^{n+\frac{1}{2}}(k)}{\hbar} \right) \psi_R^{n+\frac{1}{2}}(k). \end{aligned} \quad (54)$$

After the imaginary and real parts of wave function are calculated by (51)–(54), the polarization current $J_z^{n+(1/2)}$ is obtained by

$$\begin{aligned} J_z^{n+1}(k) &= \frac{e \hbar}{m_0} \left\{ \psi_R^{n+\frac{1}{2}}(k) \beta [\psi_I^{n+\frac{1}{2}}(k)] - \psi_I^{n+\frac{1}{2}}(k) \beta [\psi_R^{n+\frac{1}{2}}(k)] \right\} - \frac{e^2}{2m_0} \\ &\times \left[\left(\psi_R^{n+\frac{1}{2}}(k) \right)^2 + \left(\psi_I^{n+\frac{1}{2}}(k) \right)^2 \right] \\ &\times \left[A_z^{n+\frac{1}{2}} \left(i, j, k + \frac{1}{2} \right) + A_z^{n+\frac{1}{2}} \left(i, j, k - \frac{1}{2} \right) \right]. \end{aligned} \quad (55)$$

The operators α and β represent the sixth-order accurate difference formulas of the first- and second-order derivatives with respect to the z -coordinate ($\partial/\partial k$ and $\partial^2/\partial k^2$), respectively. For an arbitrary function χ , the sixth-order accurate difference formulas of the first- and second-order derivatives

are expressed as

$$\beta[\chi(k)] = \frac{1}{60\Delta z} \begin{bmatrix} \chi(k+3) - 9\chi(k+2) + 45\chi(k+1) \\ -45\chi(k-1) + 9\chi(k-2) - \chi(k-3) \end{bmatrix} \quad (56)$$

$$\alpha[\chi(k)] = \frac{1}{90\Delta z^2} \begin{bmatrix} \chi(k+3) - 13.5\chi(k+2) + 135\chi(k+1) \\ -245\chi(k) + 135\chi(k-1) \\ -13.5\chi(k-2) + \chi(k-3) \end{bmatrix}. \quad (57)$$

The stability condition of the QM system that is simulated by the FDTD simulation has been investigated in [29] and is defined as

$$\Delta t \leq \frac{2\hbar}{\frac{2\hbar^2}{m_0} \left(\frac{1}{\Delta x^2} + \frac{1}{\Delta y^2} + \frac{1}{\Delta z^2} \right) + V_{\max}} \quad (58)$$

where V_{\max} is the maximum value. In order to have a stable scheme, the time step Δt should be taken to the minimum of the EM or QM systems. In the next, the numerical stability of the proposed **E–B–A– ϕ** system is analyzed and provided as follows.

According to the updating equations of the EM fields and the auxiliary variables (39)–(50), the matrix form of the updating equation can be represented by (all the field components are set at the same time for simplicity)

$$[M_l]P^{n+1} = [M_r]P^n \quad (59)$$

where

$$P = (E_x, E_y, E_z, B_x, B_y, B_z, A_x, A_y, A_z, \phi). \quad (60)$$

M_l and M_r are expressed by (61) and (62), respectively

$$M_l = \begin{bmatrix} a & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & a & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & a & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & b & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & b & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & b & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & D_x & D_y & D_z & c \end{bmatrix} \quad (61)$$

$$M_r = \begin{bmatrix} a & 0 & 0 & 0 & D_z & -D_y & 0 & 0 & 0 & 0 \\ 0 & a & 0 & -D_z & 0 & D_x & 0 & 0 & 0 & 0 \\ 0 & 0 & a & D_y & -D_z & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & -D_z & D_y & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & D_z & 0 & -D_x & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & -D_y & D_x & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & b & 0 & 0 & D_x \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & b & 0 & D_y \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & b & D_z \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & c \end{bmatrix} \quad (62)$$

where $a = -\mu\epsilon/\Delta t$, $b = -1/\Delta t$, $c = -\mu\epsilon_\phi^2/(\Delta t\epsilon_A)$, and $D_u = \partial/\partial u$ ($u = x, y, z$) denotes the first-order derivative of u versus space.

We assume that the expression of the field components P in space domain can be described by

$$P_{i,j,k}^n = \phi_P \zeta^n e^{-j(k_x \Delta x + k_y \Delta y + k_z \Delta z)} \quad (63)$$

where ζ is the growth factor and k_u ($u = x, y, z$) is the wavenumber. Therefore, the spatial derivative of the field components $P_{i,j,k}^n$ can be approximated as

$$D_u P_{i,j,k}^n = \delta_u \phi_P \zeta^n e^{-j(k_x \Delta x + k_y \Delta y + k_z \Delta z)} \quad (64)$$

and $\delta_u = 2j \sin(k_u \Delta u/2)/\Delta u$ ($u = x, y, z$).

Substituting (63) and (64) into (59) gives

$$[M_l \zeta - M_r] P^n = M P^n = 0 \quad (65)$$

and

$$M = \begin{bmatrix} a\zeta_1 & 0 & 0 & 0 & -D_z & D_y & 0 & 0 & 0 & 0 \\ 0 & a\zeta_1 & 0 & D_z & 0 & -D_x & 0 & 0 & 0 & 0 \\ 0 & 0 & a\zeta_1 & -D_y & D_x & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \zeta_1 & 0 & 0 & 0 & D_z & -D_y & 0 \\ 0 & 0 & 0 & 0 & \zeta_1 & 0 & -D_z & 0 & D_x & 0 \\ 0 & 0 & 0 & 0 & 0 & \zeta_1 & D_y & -D_x & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & b\zeta_1 & 0 & 0 & -D_x \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & b\zeta_1 & 0 & -D_y \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & b\zeta_1 & -D_z \\ 0 & 0 & 0 & 0 & 0 & 0 & D_x \zeta & D_y \zeta & D_z \zeta & c\zeta_1 \end{bmatrix} \quad (66)$$

where $\zeta_1 = \zeta - 1$.

To determine the nonzero solution of (66), the determinant of the coefficient matrix M in (66) should be zero. The polynomial of the determinant of the coefficient matrix M is obtained through many simplified operations and expressed as

$$a\zeta^3(\zeta - 1)[(\sigma_x^2 + \sigma_y^2 + \sigma_z^2)\zeta - bc(\zeta - 1)^2] \times [(\sigma_x^2 + \sigma_y^2 + \sigma_z^2)\zeta - ab(\zeta - 1)^2]^2. \quad (67)$$

According to the von Neuman stability analysis method, the module value of the growth factor ζ should be no more than 1. For the first polynomial factor of (67), the growth factors are $\zeta_{1,2,3} = 0$, and for the second polynomial factor of (67), the growth factor is $\zeta_4 = 1$, thereby meeting the numerical stability requirement.

For the third polynomial factor of (67), the growth factor ζ is obtained by

$$\zeta_{5,6} = \frac{-(\sigma_x^2 + \sigma_y^2 + \sigma_z^2 + 2bc) \pm \sqrt{(\sigma_x^2 + \sigma_y^2 + \sigma_z^2 + 2bc) - 4b^2c^2}}{-2bc}. \quad (68)$$

As mentioned above, the module value of the growth factor $\zeta_{5,6}$ in (68) should be no more than 1. Then, the following condition should be satisfied:

$$4b^2c^2 \geq (\sigma_x^2 + \sigma_y^2 + \sigma_z^2 + 2bc). \quad (69)$$

Substituting $\delta_u = 2j \sin(k_u \Delta u/2)/\Delta u$ ($u = x, y, z$) into (69), thus,

$$\left[\frac{\sin(k_x \Delta x/2)}{\Delta x/2} \right]^2 + \left[\frac{\sin(k_y \Delta y/2)}{\Delta y/2} \right]^2 + \left[\frac{\sin(k_z \Delta z/2)}{\Delta z/2} \right]^2 \leq 4b^2c^2. \quad (70)$$

Since $\sin(k_u \Delta u/2)$ can be at most one, then we get

$$\left[\frac{1}{\Delta x/2} \right]^2 + \left[\frac{1}{\Delta y/2} \right]^2 + \left[\frac{1}{\Delta z/2} \right]^2 \leq 4b^2c^2. \quad (71)$$

As $b = -1/\Delta t$ and $c = -\mu\epsilon_\phi^2/(\Delta t^2\epsilon_A)$, we get

$$bc = \mu\epsilon_\phi^2/(\Delta t^2\epsilon_A). \quad (72)$$

Substituting (72) into (71), we get

$$\Delta t = \sqrt{\mu\epsilon_\phi^2/\epsilon_A} \frac{1}{\sqrt{(1/\Delta x)^2 + (1/\Delta y)^2 + (1/\Delta z)^2}}. \quad (73)$$

Although the values of permittivity ϵ_A and ϵ_ϕ are related to the spatial location of \mathbf{A} and ϕ , respectively, they are equal to the same value ϵ . Then, the inequality of time step Δt is derived as

$$\Delta t = \sqrt{\mu\epsilon} \frac{1}{\sqrt{(1/\Delta x)^2 + (1/\Delta y)^2 + (1/\Delta z)^2}}. \quad (74)$$

For the fourth polynomial factor of (67), the growth factor ζ is obtained by

$$\zeta_{7,8} = \zeta_{9,10} = \frac{-(\sigma_x^2 + \sigma_y^2 + \sigma_z^2 + 2ab) \pm \sqrt{(\sigma_x^2 + \sigma_y^2 + \sigma_z^2 + 2bc) - 4a^2b^2}}{-2ab}. \quad (75)$$

Similarly, according to (75), we can get the following:

$$\left[\frac{1}{\Delta x/2} \right]^2 + \left[\frac{1}{\Delta y/2} \right]^2 + \left[\frac{1}{\Delta z/2} \right]^2 \leq 4a^2b^2. \quad (76)$$

As $a = -\mu\epsilon/\Delta t$ and $b = -1/\Delta t$, we get

$$ab = \mu\epsilon/(\Delta t^2). \quad (77)$$

Substituting (77) into (76), then the inequality of the time step Δt is derived as

$$\Delta t = \sqrt{\mu\epsilon} \frac{1}{\sqrt{(1/\Delta x)^2 + (1/\Delta y)^2 + (1/\Delta z)^2}}. \quad (78)$$

According to (74) and (78), we can conclude that the proposed **E–B–A– ϕ** system satisfies the Courant–Friedrich–Levy (CFL) limitation of the conventional FDTD method.

In conclusion, to have a stable scheme, the time step Δt should be taken to the minimum of the EM system (58) or QM system (78).

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